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NUMERICAL CALCULATIONS
FOR THE EVALUATION OF MÖSSBAUER SPECTRA

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1.3. The Mössbauer effect is most frequently observed on the measured absorption spectra. The Mössbauer parameters of the measured spectra are the position, width and shape of the absorption lines, the maximum absorption /amplitude/ and the base line background.

For thin absorber the absorption lines are shaped like Lorentzian curves. All the lines in the spectra considered in the following are assumed to have Lorentzian shape. The positions and intensities of the observed lines are determined by the eigenvalues and eigenvectors of the hyperfine interaction Hamiltonian of the nuclear levels, respectively.

The hyperfine interaction Hamiltonian is given by the sum (1) [1]

$$\hat{H} = \hat{H}_Q + H_M \quad (1)$$

If the coordinate system is chosen to be such that the z-axis points in the direction of the component V_{zz} of the electric field gradient /Fig.1/, then the

contribution from the quadrupole interactions is defined as

$$\hat{H}_Q = \frac{eQV_{zz}}{4I(2I-1)} [3I_z^2 - I(I+1) + \eta(I_x^2 - I_y^2)]$$

and the contribution from the magnetic interactions is defined as

$$\hat{H}_M = -g\mu_N H_i [I_z \cos\theta + (I_x \cos\varphi + I_y \sin\varphi) \sin\theta]$$

where

Q = the electric quadrupole momentum

e = the proton charge

g = the nuclear magnetic g-factor

I = the nuclear spin

μ_N = the nuclear magneton

$\eta = \frac{V_{xx} - V_{yy}}{V_{zz}}$ = the asymmetry parameter

θ, φ = the polar coordinates of the magnetic field

H_i relative to the principal axes of the electric field gradient tensor

I_x, I_y, I_z are the angular momentum operators. The

components of the electric field gradient are chosen

to be such that we have $|V_{zz}| \geq |V_{yy}| \geq |V_{xx}|$,

hence $0 \leq \eta \leq 1$

For $I = 1/2$ and $I = 3/2$ e.g. ^{57}Fe and ^{119}Sn

the matrix elements of the Hamiltonian defined by /1/

can be written in the form [2]

m'	m	
	1/2	- 1/2
1/2	b_{11}	b_{12}
-1/2	b_{21}	b_{22}

(I)

m'	m			
	3/2	1/2	-1/2	-3/2
3/2	a_{11}	a_{12}	a_{13}	0
1/2	a_{21}	a_{22}	a_{23}	a_{13}
-1/2	a_{13}	a_{32}	a_{33}	a_{12}
-3/2	0	a_{13}	a_{21}	a_{44}

(II)

where

$$b_{11} = -1/2 \beta \cos \theta$$

$$b_{22} = 1/2 \beta \cos \theta$$

$$b_{12} = -1/2 \beta \sin \theta \exp(-i\varphi)$$

$$b_{21} = -1/2 \beta \sin \theta \exp(i\varphi)$$

$$a_{11} = 3 A - 3/2 d \cos \theta$$

$$a_{22} = -3 A - 1/2 d \cos \theta$$

$$a_{33} = -3 A + 1/2 d \cos \theta$$

$$a_{44} = 3 A + 3/2 d \cos \theta$$

$$a_{12} = -\sqrt{3}/2 d \sin \theta \exp(-i\varphi)$$

$$a_{21} = -\sqrt{3}/2 d \sin \theta \exp(i\varphi)$$

$$a_{23} = -d \sin \theta \exp(-i\varphi)$$

$$a_{32} = -d \sin \theta \exp(i\varphi)$$

$$a_{13} = \sqrt{3} \eta A$$

$$d = g_{3/2} \mu_N \cdot H_i$$

$$\beta = g_{1/2} \mu_N \cdot H_i$$

$$A = e Q V_{zz} / 4 I (2 I - 1)$$

The positions /TE/ of the absorption lines are given in terms of the eigenvalues of the above matrices, by

$$TE(3/2, i; 1/2, j) = \lambda(3/2, i) - \lambda(1/2, j) \quad (2)$$

while the intensities /4/ are expressed in terms of the eigenvectors /3/ in the form

$$\psi(3/2, i) = \begin{vmatrix} c_{3/2, i}^{3/2} \\ c_{3/2, i}^{1/2} \\ c_{3/2, i}^{-1/2} \\ c_{3/2, i}^{-3/2} \end{vmatrix} = c_{3/2, i}^m; \psi(1/2, j) = \begin{vmatrix} c_{1/2, j}^{1/2} \\ c_{1/2, j}^{-1/2} \end{vmatrix} = c_{1/2, j}^{m'} \quad (3)$$

$$P(Q, \varphi; 3/2, i; 1/2, j) = \left| \sum_{m, m'} c_{1/2, j}^{m'} \cdot c_{3/2, i}^m \cdot M_{m' m} \right|^2 \quad (4)$$

hence we get in the case of magnetic dipole transition

$$M_{m' m} = \langle 1/2 m'; L, m | 3/2, m \rangle \cdot X_z^m$$

The symbol \langle / \rangle stands here for the Clebsch-Gordan coefficient, while X is the vector normal to the direction of the γ -radiation. It can be decomposed to the contributions

$$X'_{\varphi} = -\frac{1}{\sqrt{2}} e^{i\varphi}$$

$$X_{\varphi}^0 = 0$$

$$X'_{\theta} = \frac{i}{\sqrt{2}} \cos \theta e^{i\varphi}$$

$$X_{\theta}^0 = i \sin \theta$$

$$X'^{-1}_{\varphi} = -\frac{1}{\sqrt{2}} e^{-i\varphi}$$

$$X'^{-1}_{\theta} = -\frac{i}{\sqrt{2}} \cos \theta e^{-i\varphi}$$

In the case of polycrystalline samples, the crystal grains are randomly distributed, thus the intensities /4/ of the lines are evaluated by integration over θ and φ as

$$\bar{p}(3/2, i; 1/2, j) = \iint_0^{2\pi} p(\theta, \varphi; 3/2, i; 1/2, j) \cdot \sin \theta d\theta d\varphi \quad /5/$$

The eigenvalues of the matrix /I/ can be easily evaluated and we get $TE_{1,2} = \pm 1/2\beta$

In the general case the characteristic equation for /II/ is given by the fairly complicated formula

$$X^4 + aX^2 + bX + c = 0 \quad /6/$$

Where

$$a = -[18A^2(1 + 1/3\eta^2) + 5/2 d^2]$$

$$b = -12Ad^2 \cos^2 \theta - 3\eta Ad^2 \sin^2 \theta \cdot \cos^2 \varphi + 6Ad^2 \sin^2 \theta$$

$$c = (3\eta^2 A^2 - 3/4 d^2 \sin^2 \theta)^2 + 3\eta^2 A^2 (18A^2 + 5/2 d^2 \cos^2 \theta) + d^2 \sin^2 \theta (27A^2 + 9/8 d^2 \cos^2 \theta) + 18\eta A^2 d^2 \sin^2 \theta \cdot \cos^2 \varphi + 81A^4 + 9/16 d^4 \cos^4 \theta - 45/2 A^2 d^2$$

Practically, it is impossible to solve the equation /6/ for the general case. Let us see therefore the most important special cases namely,

$$a/ \quad H \neq 0, \quad \theta = \varphi = 0$$

for which the eigenvalue equation /6/ has the form

$$\lambda^4 - 18A^2(1 + 1/3\eta^2)\lambda^2 + 81A^2(1 + 1/3\eta^2)^2 = 0 \quad /7/$$

$$\text{and } \lambda_{1,2} = 3A(1 + 1/3\eta^2)^{1/2}$$

$$\lambda_{3,4} = -3A(1 + 1/3\eta^2)^{1/2}$$

$$b/ \quad A = 0; \quad \theta = \varphi = 0$$

then eq. /6/ becomes

$$\lambda^4 - 5/2 d^2 \lambda^2 + 9/16 d^4 = 0 \quad /8/$$

$$\lambda_{1,2} = \pm 3/2 d$$

$$\lambda_{3,4} = \pm 1/2 d$$

$$c/ \quad A \neq 0; \quad \theta = \varphi = 0; \quad \eta = 0 \text{ and } A \ll d$$

with eq. /6/ reducing to

$$\lambda^4 - 5/2 d^2 \lambda^2 - 12A d^2 \lambda + 9/16 d^4 = 0 \quad /9/$$

We try to find the solution in the form $\lambda_i = \lambda_i^0 + \Delta\lambda_i$, where λ_i is the solution to eq. /8/. Substituting λ_i into the expression /9/ and omitting the small, second order terms, we get $\Delta\lambda_i = \frac{12A d^2}{4\lambda_i^0 - 5d^2}$ from which the roots are obtained as

$$\lambda_1 = 3/2 d + 3A$$

$$\lambda_2 = 1/2 d - 3A$$

$$\lambda_3 = -1/2 d - 3A$$

$$\lambda_4 = -3/2 d + 3A$$

d/ $\varphi = 0$, $\eta = 0$, $A \neq 0$, $\theta \neq 0$ and $A \ll d$

. The form /6/ is then

$$\lambda^4 - 5/2 d^2 \lambda^2 + 6A d^2 (1 - 3 \cos^2 \theta) + 9/16 d^4 = 0$$

Using again the substitution and omission applied in the case c/, we find,

$$\Delta \lambda_i = \frac{6A d^2 (1 - 3 \cos^2 \theta)}{4 \lambda_i^2 - 5 d^2}$$

and hence the roots can be defined as

$$\lambda_1 = 3/2 d + 3/2 A (1 - 3 \cos^2 \theta)$$

$$\lambda_2 = 1/2 d - 3/2 A (1 - 3 \cos^2 \theta)$$

$$\lambda_3 = -1/2 d - 3/2 A (1 - 3 \cos^2 \theta)$$

$$\lambda_4 = -3/2 d + 3/2 A (1 - 3 \cos^2 \theta)$$

e/ If the magnetic field lies in the direction of one of the principal axes of the electric field gradient tensor, the eigenvalue equation can be written in the form

$$\lambda^4 - [18A^2(1 + 1/3\eta^2) + 5/2d^2]\lambda^2 - 12Ad^2\lambda +$$

/10/

$$+ 81A^4(1 + 1/3\eta^2)^2 + 9/16d^4 + 9/2d^2A^2(\eta^2 - 5)$$

The solutions to equations of the form $y^4 + py^2 +$
 $+ qy + r = 0$ can be written as

$$y_1 = 1/2(\sqrt{z_1} + \sqrt{z_2} + \sqrt{z_3})$$

$$y_2 = 1/2(\sqrt{z_1} - \sqrt{z_2} - \sqrt{z_3})$$

$$y_3 = 1/2(-\sqrt{z_1} + \sqrt{z_2} - \sqrt{z_3})$$

$$y_4 = 1/2(-\sqrt{z_1} - \sqrt{z_2} + \sqrt{z_3})$$

where z_i stands for the roots of the equation
 $z^3 + 2pz^2 + (p^2 - 4r)z - q^2 = 0$ which in the present case
reads

$$z^3 - [5d^2 + 12A^2\eta^2 + 36A^2]z^2 + d^2[4d^2 + 12A^2\eta^2 + 160A^2]z - 144A^2d^4 = 0$$

/11/

On introducing $d^2 = a$, the rearrangement of /11/ with
respect to the equal powers of the products of a and z ,
leads to

$$z(z^2 - 5az + 4a^2) - 12A^2\eta^2 z(z-a) + 3A^2(5az - z^2 - 4a^2) = (z - 36A^2) \\ [z(z-a) - 4a(z-a)] - 12A^2\eta^2 z(z-a) = 0$$

that is, $z = a$ is a root of eq. /11/.

It is now easy to find the two other roots and the solution to /11/ can be written as

$$y_{1,2} = 1/2 d^{\pm} [1/3A + d/2 + 3A^2\eta^2]^{1/2}$$

$$y_{3,4} = -1/2 d^{\pm} [1/3A - d/2 + 3A^2\eta^2]^{1/2}$$

With this we have actually given all the possible analytical solutions to eq. /6/. If none of the assumptions made in a/, b/, c/, d/, or e/ is valid, only numerical methods can help. The numerical solutions can be then utilized for the evaluation of the positions of the hyperfine lines in the Mössbauer spectra by making use of the formula /2/.

§ 2. The transition probabilities can be given /3/ in tabulated form as follows.

for $H = 0$, $A \neq 0$

Transition	I/e/	I/polycrystal/
$\pm 3/2 \rightarrow \pm 1/2$	$3/2(1 + \cos^2\theta)$	1
$\pm 1/2 \rightarrow \pm 1/2$	$1 + 3/2 \sin^2\theta$	1

where θ is the angle between the symmetry axis and the direction of the γ -ray.

for $H \gg A$

Transition	I/ θ /	I/polycrystal/
$3/2 \rightarrow 1/2$		
$-3/2 \rightarrow -1/2$	$9/4(1+\cos^2\theta)$	3
$1/2 \rightarrow 1/2$		
$-1/2 \rightarrow -1/2$	$3 \sin^2 \theta$	2
$-1/2 \rightarrow 1/2$		
$1/2 \rightarrow -1/2$	$3/4(1+\cos^2\theta)$	1

where θ is the angle between the magnetic field and the direction of the γ -ray.

§ 3. In the computer programs the method of least squares developed by Silin /4/ was applied. The ALGOL and FORTRAN versions of the method are presented in the Annexes I. and II. The advantages of the method are its clarity and the fact that it can be applied to different problems upon resriting only a single, namely the "sqz" procedure.

The following notations are used

$$S = 1/2 \sum_i \left(\frac{y_i - x_i}{\text{sig}_i} \right)^2$$

where y_i are the measured points

f_i are the calculated values

sig_i are the errors of the experimental points.

$$Z_{ik} = \frac{\partial^2 f}{\partial \alpha_i \partial \alpha_k}$$

n = the number of parameters

n_1 = maximum number of steps within an iteration

n_2 = minimum number of iterations without

n_3 = maximum number of iterations after the program stops irrespective of the accuracy.

eps = accuracy / if $\text{kappa} \leq \text{abs}(\text{eps})$, the program stops

$a[i]$ = the value of the parameters

$l[i]$ = during an iteration the correction of the parameters cannot be greater than $l[i]$. The starting values are specified by the programmer.

$\text{sigma}/i/ = \sqrt{Z_{ii}} =$ the statistical errors of the parameters

$r[i]$ = correlation factors

$da/i/ =$ the corrections of the parameters = $-\text{lambda} / Z^{-1} g / i$

$$\text{kappa} = \max_i \left| \frac{(Z^{-1} g)_i}{\text{sigma} \alpha[i]} \right|$$

$$\text{lambda} = \frac{1}{\max_i \left(1, \left| \frac{(Z^{-1} g)_i}{l[i]} \right| \right)}$$

procedures :

funilim - dispatcher part of the program
 monitor - printout of partial results
 mconv - inversion of the symmetrical matrix
 mvmult - calculation of the $da = (z^{-1}G)_i$ product
 fix - fixing of the parameter values for which
 $1/i/ = 0$
 sgz - calculation of the values of s, G, and z

§ 4. In this paragraph the /sgz/ procedures for the different practical cases are described.

a/ The spectrum is assumed to be the superposition of N Lorentzian curves, and can be thus described by the function

$$f_j = (A_0 + Bx_j) \left[1 - \sum_{k=1}^N \frac{\alpha_k}{(x_j - \delta_k)^2 + \gamma_k^2/4} \right] \quad /12/$$

the sequence of the parameters is

A_0 - is the ground-line
 α_k - N magnitudes
 δ_k - N line-positions
 γ_k - N line-widths
 B - the slope of the ground line

b/ The assumption a/ imposes often difficult problems /e.g. the presence of many poorly resolved peaks to the program. In this case use can be made of the expression in § 1.c/ which describes the relative positions of the six lines in the so called 6-line Zeeman pattern. If the spectrum is produced by the superposition of W Zeeman patterns, it can be described by the function

$$f(x_j) = (A_0 + Bx_j) \left[1 - \sum_{i=1}^6 \sum_{k=1}^W \frac{\alpha_k \cdot k_i}{(x_j - \delta_{ik})^2 + \gamma^2/4} \right] \quad /13/$$

where $\delta_{ik} = \delta_{ik}(\epsilon_k, H_k, \delta_k)$

the sequence of the parameters is

γ - is the line-width,

A_0 - the ground line,

α_k - w magnitudes,

H_k - w magnetic fields /in $\frac{\text{kilo Gauss}}{\text{mm/sec}}$ /

δ_k - w line-positions /in channels/,

ϵ_k - w quadrupole splittings /in channels/,

B - the slope of the groundline,

k_i - the relative magnitude of the Zeeman pattern lines,

a, b, c - the coefficients at H_i for the Zeeman pattern lines /e.g. for Fe^{57} : 0.01615, 0.00923, 0.00253/

/Annexes III. and IV./

c/ Finally, if the numerical solution of the eigenvalue problem is the only possible method, the program described in Annexo V can be used. This program is suitable for the least square fit of two 6-line Zeeman patterns and two 8-line patterns to the function

$$\begin{aligned}
 f(x_j) = & (A_0 + Bx_j) \left[1 - \sum_{i=3}^4 \alpha_i \left(\frac{K_1}{(x_j + \alpha H_i - \delta_i + \epsilon_i)^2 + \delta_i^2/4} + \right. \right. \\
 & \frac{K_2}{(x_j + \beta H_i - \delta_i - \epsilon_i)^2 + \delta_i^2/4} + \frac{K_3}{(x_j + \gamma H_i - \delta_i - \epsilon_i)^2 + \delta_i^2/4} + \\
 & \frac{K_3}{(x_j - \gamma H_i - \delta_i - \epsilon_i)^2 + \delta_i^2/4} + \frac{K_2}{(x_j - \beta H_i - \delta_i - \epsilon_i)^2 + \delta_i^2/4} + \\
 & \left. \left. \frac{K_1}{(x_j - \alpha H_i - \delta_i + \epsilon_i)^2 + \delta_i^2/4} \right) - \sum_{k=1}^2 \alpha_k \left(\frac{P_{1k}}{(x_j - \delta_k - T_{1k})^2 + \delta_k^2/4} + \right. \right. \\
 & \frac{P_{12k}}{(x_j - \delta_k - T_{12k})^2 + \delta_k^2/4} + \frac{P_{13k}}{(x_j - \delta_k - T_{13k})^2 + \delta_k^2/4} + \\
 & \frac{P_{14k}}{(x_j - \delta_k - T_{14k})^2 + \delta_k^2/4} + \frac{P_{21k}}{(x_j - \delta_k - T_{21k})^2 + \delta_k^2/4} + \frac{P_{22k}}{(x_j - \delta_k - T_{22k})^2 + \delta_k^2/4} + \\
 & \left. \left. \frac{P_{23k}}{(x_j - \delta_k - T_{23k})^2 + \delta_k^2/4} + \frac{P_{24k}}{(x_j - \delta_k - T_{24k})^2 + \delta_k^2/4} \right) \right]
 \end{aligned}$$

the sequence of the parameters is

A_0 - the ground-line

$\left. \begin{matrix} \gamma_k \\ \gamma_i \end{matrix} \right\}$ - four line-widths /in channels/

$\left. \begin{matrix} a_k \\ c_i \end{matrix} \right\}$ - four magnitudes

H_k - two magnetic fields /in kiloGauss/

H_i - two magnetic fields /in $\frac{kG \cdot channel}{mm/sec}$ /

$\left. \begin{matrix} \delta_k \\ \delta_i \end{matrix} \right\}$ - four isomer shifts /in channels/

\mathcal{E}_k - two quadrupole splitting $\mathcal{E} = A$ /in channels/

\mathcal{E}_i - two quadrupole splitting $\mathcal{E} = \frac{1}{4} e^2 Q V_{zz}$ /in channels/

$\left. \begin{matrix} Q_k \\ \varphi_k \end{matrix} \right\}$ - the polase wordinates /in radians/

η_k - two assymetry parameters

B - the slope of the ground-line

for the i-th components one must give the coefficients

K and a,b,c /see § 4.b/

Annexe V.

§ 5. An ever more frequent problem is the evaluation of the contribution from the crystal field to the electric field gradient tensor for given lattice parameters and charge distribution.

The contribution to the tensor V_{ik} can be defined as

$$V_{xx} = \sum \frac{1}{r^3} \left(\frac{3x^2}{r^2} - 1 \right); \quad V_{xy} = V_{yx} = \sum \frac{3xy}{r^5};$$

$$V_{yy} = \sum \frac{1}{r^3} \left(\frac{3y^2}{r^2} - 1 \right); \quad V_{xz} = V_{zx} = \sum \frac{3xz}{r^5};$$

$$V_{zz} = \sum \frac{1}{r^3} \left(\frac{3z^2}{r^2} - 1 \right); \quad V_{yz} = V_{zy} = \sum \frac{3yz}{r^5};$$

The program, which works for orthogonal coordinate systems, only, calculates the lattice sum of the tensor V_{ik} up to the desired coordination sphere. Then it diagonalizes the sum and evaluates in addition to the eigenvalues, the eigenvectors, too. Finally it yields the values of the quadrupole splitting $\mathcal{E} = \frac{1}{2} e^2 V_{zz} \cdot Q \cdot (1 + 1/3 \eta^2)^{1/2}$ and the asymmetry parameter $\eta = \frac{V_{xx} - V_{yy}}{V_{zz}}$

the sequence of parameters for the Annexe VI. is

- N - is the number of atom in the unit cello,
- NA - the number of steps with the change of the
lattice parameters,
- NW - the number of the atom for which the EFG
tensor will be computed,
- A,B,C - the lattice parameters,
- V - the nuclear quadrupole moment,
- L_1, L_2, L_3 - the value of the steps of the lattice para-
meter change,
- M - the number of neighboring unit cells around
the central one in the direction x, y, z
- x_i, y_i, z_i - the coordinats of the atoms in the unit cell
- Si - the charges of the atoms in the unit cell

the sequence of the parameters for the Annexe VII.

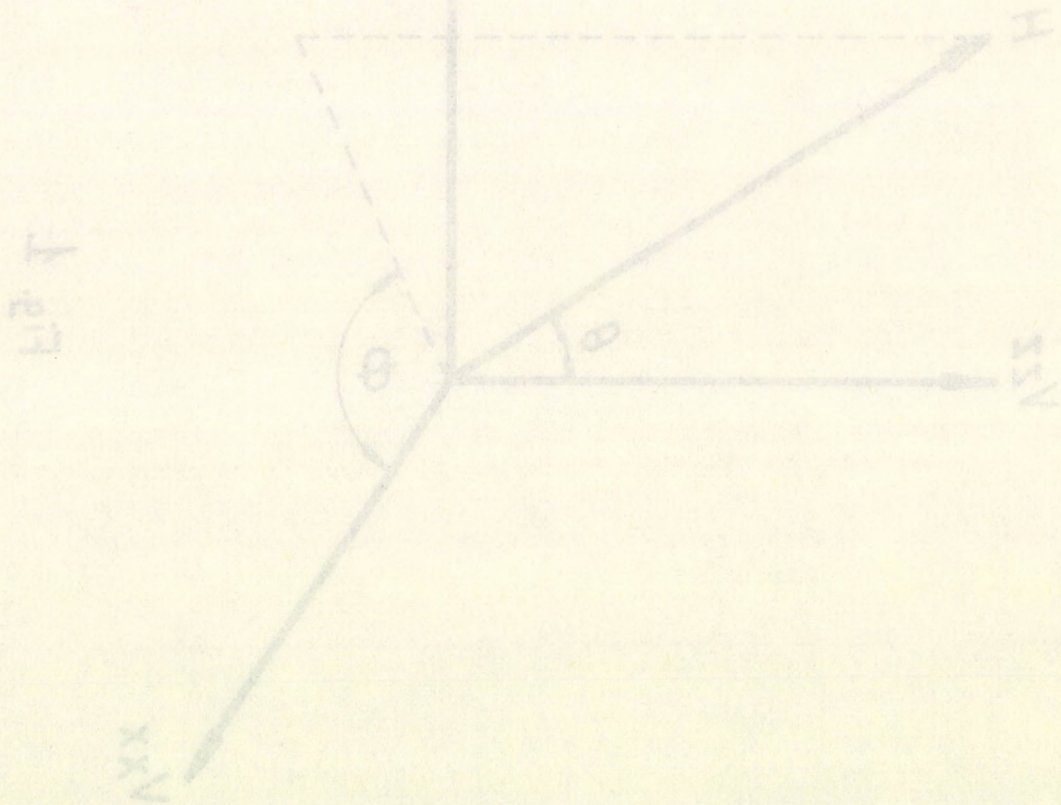
- nn - the number of the repetition of the evaluation
- n - N
- xa- NA
- xb- the number can be used to identify the users
program
- w - NW
- a,b,c, - A,B,C etc.

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задач методом наименьших квадратов. Препринт
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Figure Captions

- Fig 1. The polar coordinates of the internal magnetic field relative to the principal axes of the electric field gradient tensor



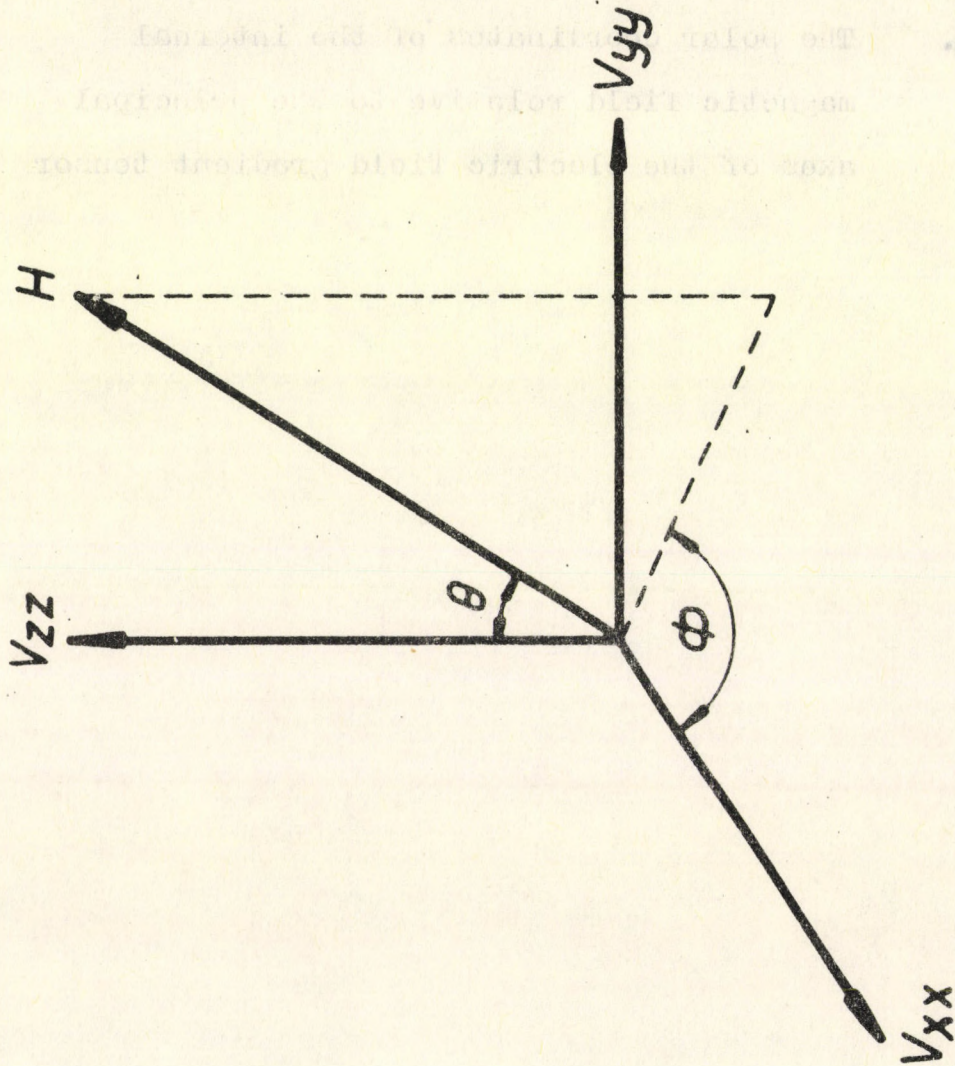


Fig. 1

Annexes I.

```
'procedure' form(z,g,df,y,sig,n);  
  'value' y,sig,n;'real' y,sig;  
  'integer' n;'real' 'array' z,g,df;  
  'begin' 'integer' i,k,l;  
    l:=1;y:=y/sig;  
    'for' i:=1 'step' 1 'until' n 'do'  
      'begin' g[i]:=g[i]+df[i]*y/sig;  
      'for' k:=1 'step' 1 'until' i 'do'  
        'begin' z[i]:=z[i]+df[i]/sig*  
          (df[k]/sig);l:=l+1;  
        'end' k;  
      'end' i;  
    'end' form;
```

```
'procedure' fix(z,l,c,n);'value' c,n;  
  'real' 'array' z,l;'real' c;'integer' n;  
  'begin' 'integer' i,k;  
    'for' i:=1 'step' 1 'until' n 'do'  
      'if' l[i]=0 'then'  
        'for' k:=1 'step' 1 'until' n 'do'  
          z['if' k'le'i 'then'  $1*(i-1)/2+k$  'else'  $k*(k-1)/2+1$ ]:=   
            'if'  $i \neq k$  'then' 0 'else' c;  
        'end' k;  
      'end' i;  
    'end' fix;
```


'procedure' meconv(z,n):

 'value' n; 'integer' n; 'real' 'array' z;

 'begin' 'integer' i,k,l; 'real' c,d;

 diagonalization:

 'for' i:=1 'step' 1 'until' n-1 'do'

 'for' k:=n 'step' -1 'until' i+1 'do'

 'begin'

 c:=z[k*(k-1)/2+1]/z[i*(i+1)/2];

 'for' l:=k 'step' -1 'until' i 'do'

 z[k*(k-1)/2+1]:=z[k*(k-1)/2+1]-

 z['if' l>i 'then' l*(l-1)/2+1

 'else' i*(i-1)/2+1]*c;

 z[k*(k-1)/2+1]:=-c

 'end' i,k;

 multiplication:

 'for' i:=1 'step' 1 'until' n 'do'

 'for' k:=1 'step' 1 'until' n 'do'

 'begin' d:=0;

 'for' l:=k 'step' 1 'until' n 'do'

 'begin'

 c:=1/z[l*(l+1)/2];

 'if' l#1 'then'

 c:=c*z[l*(l-1)/2+1];

 'if' l#k 'then'

 c:=c*z[l*(l-1)/2+k];

 d:=d+c;

 'end' l;

 z[k*(k-1)/2+1]:=d;

 'end' i,k

 'end' meconv;


```

'procedure' mvmult(z,g,da,n);
  'value' n; 'integer' n; 'real' 'array' z,g,da;
  'begin' 'integer' i,1;
    'for' i:=1 'step' 1 'until' n 'do'
      'begin' da[i]:=0;
        'for' l:=1 'step' 1 'until' n 'do'
          da[i]:=da[i]+g[l]*z['if' i'ge'l 'then'
            i*(i-1)/2+1 'else' l*(l-1)/2+1];
        'end' l,1;
      'end' i,1;
  'end' mvmult;

```

```

'procedure' funlim(s,g,z,n,n1,n2,n3,eps,a,l,sigma,r,da,kappa,lambda,
  sgz,monitor);
  'value' n,n ,n2,n3,eps; 'integer' n,n1,n2,n3;
  'real' s,eps,kappa,lambda;
  'real' 'array' g,z,a,l,sigma,r,da;
  'procedure' sgz,monitor;
  'begin' 'real' t,max,gt,olds,t1;
    'integer' i,n1,n2,n3;
    nn2:=0;nn3:=0;
    sgz(s,g,z,a,n);t1:=1;
    'goto' shift;
  control:nn1:=1;t1:=1;
  repeat:sgz(s,g,z,a,n);
    'if' nn1>n1 'then' 'goto' shift;
    t:=-2*(s-olds-gt);
    'if' 0.59*t+gt'le'0 'then' 'goto' shift;
    t:=-1.5*gt/t;'if' t<0.25 'then' t:=0.25;
    gt:=gt*t;t1:=t1*t;nn2:=0;
    'for' i:=1 'step' 1 'until' n 'do'
      'begin' a[i]:=a[i]-da[i];l[i]:=l[i]*t;
        da[i]:=da[i]*t;a[i]:=a[i]+da[i];
      'end' i;nn1:=nn1+1;
      'goto' repeat;
  shift:fix(z,l,1,n);
  'for' i:=1 'step' 1 'until' n 'do'
    r[i]:=z[i*(i+1)/2];
    mconv(z,n);

```



```

'for' i:=1 'step' 1 'until' n 'do'
  r[i]:=r[i]*z[i*(i+1)/2];
  fix(z,1,0,n);
  'if' eps>0 'then'
    'for' i:=1 'step' 1 'until' n 'do'
      sigma[i]:=sqrt(z[i*(i+1)/2]);
      mvmult(z,g,da,n);
      maX:=1;kappa:=0;
      'for' i:=1 'step' 1 'until' n 'do' 'if' l[i]#0
        'then' 'begin'
          'if' abs(da[i]/l[i])>maX 'then'
            maX:=abs(da[i]/l[i]);
          'if' abs(da[i]/sigma[i])>kappa 'then'
            kappa:=abs(da[i]/sigma[i]);
          'end' i;lambda:=1/maX;gt:=0;
        'for' i:=1 'step' 1 'until' n 'do' 'if' l[i]#0
          'then' 'begin' 'if' nn2'ge'n2 'then' 'begin'
            'if' abs(da[i]/l[i])>.25*maX
              'then' l[i]:=4*l[i];'end';
            da[i]:=-da[i]*lambda;
            gt:=gt+da[i]*g[i]
          'end' i;
        'if' test(2) 'then' 'go to' L1;
        'if' nn3=0'or' nn3=n3 'or' kappa'le' 0.2 'then'
          L1:monitor(s,g,z,n,nn3,eps,a,1,sigma,r,da,gt,kappa,lambda,t1);
          'if' kappa'le'abs(eps) 'or'nn3'ge'n3 'or' gt 'ge' 0
            'then' 'goto' exit;
          'for' i:=1 'step' 1 'until' n 'do'
            a[i]:=a[i]+da[i];
          olds:=s;nn2:=nn2+1;nn3:=nn3+1;
          'goto' control;
exit:'end' fumilin;

```


Annexes II.

```

SUBROUTINE FORM(Z,G,F,Y,SIG,N,N9)
DIMENSION DF(N),G(N),Z(N9)
L=1
Y=Y/SIG
DO 20 I=1,N
G(I)=G(I)+DF(I)*Y/SIG
DO 299 K=1,I
Z(L)=Z(L)+DF(I)/SIG*(DF(K)/SIG)
L=L+1
299 CONTINUE
20 CONTINUE
RETURN
END

```

```

SUBROUTINE FIX(Z,L,C,N,N9)
INTEGER C
REAL L
DIMENSION Z(N9),L(N)
DO 21 I=1,N
IF(L(I)) 23,22,23
22 DO 296 K=1,N
IF(K-I) 24,24,25
24 IF(I-K) 26,27,26
26 Z(I*(I-1)/2+K)=0
GO TO 28
27 Z(I*(I-1)/2+K)=C
GO TO 28
25 IF(I-K) 29,297,29
29 Z(K*(K-1)/2+I)=0
GO TO 28
297 Z(K*(K-1)/2+I)=C
28 CONTINUE
296 CONTINUE
23 CONTINUE
21 CONTINUE
RETURN
END

```


Annex II.

```

SUBROUTINE MCONV(Z,N,N9)
  DIMENSION Z(N9)
  DO 30 I=1,N-1
    DO 30 K=I+1,N
      M=N-K+1+I
      C=Z(M*(M-1)/2+I)/Z(I*(I+1)/2)
      DO 33 L=1,M
        J=M-L+1
        IF (J-I) 32,32,31
31      Z(M*(M-1)/2+J)=Z(M*(M-1)/2+J)-Z(J*(J-1)/2+I)*C
        GO TO 33
32      Z(M*(M-1)/2+J)=Z(M*(M-1)/2+J)-Z(I*(I-1)/2+J)*C
33      CONTINUE
      Z(M*(M-1)/2+I)=-C
30    CONTINUE

    DO 34 I=1,N
      DO 314 K=I,N
        D=0
        DO 35 L=K,N
          C=1/Z(L*(L+1)/2)
          IF(L-I) 36,37,36
36        C=C*Z(L*(L-1)/2+I)
37        IF (L-K) 38,39,38
38        C=C*Z(L*(L-1)/2+K)
39        D=D+C
35      CONTINUE
      Z(K*(K-1)/2+I)=D
314    CONTINUE
34    CONTINUE
  RETURN
  END

```



```

SUBROUTINE MVMULT(Z,G,DA,N,N9)
  DIMENSION Z(N9),G(N),DA(N)
  DO 40 I=1,N
    DA(I)=0
    DO 40 L=1,N
      IF(I-L) 41,42,42
42    DA(I)=DA(I)+G(L)*Z(I*(I-1)/2+L)
      GO TO 40
41    DA(I)=DA(I)+G(L)*Z(L*(L-1)/2+I)
40    CONTINUE
  RETURN
  END

```

```

SUBROUTINE FUMILIM(G,Z,N,N1,N2,N3,EPS,A,L,SIGMA,R,DA,KAPPA,
CLAMBDA,BETA,Y,B,TETA,N9,W,SZ,CIS)
  INTEGER B,ETA,TETA,W,CIS,Y
  REAL KAPPA,LAMBDA,T,MAX,T1,L
  DIMENSION G(N),A(N),L(N),SIGMA(N),R(N),DA(N),Z(N9),
CBETA(CIS),Y(CIS),SZ(9)
  S=0
  NN2=0
  NN3=0
  CALL SGZ(S,G,Z,A,N,Y,BETA,B,L,N9,W,SZ,CIS)
  T1=1
  GO TO 50
51  NN1=1
  T1=1

```



```

52 CALL SGZ(S,G,Z,A,N,Y,BETA,B,L,N9,W,SZ,CIS)
   IF (NN1-N1) 53,53,54
54 GO TO 50
53 T=(S-OLDS-GT)*2.0
   FI=0.59*T+GT
   IF (FI) 50,50,56
56 T=-1.5*GT/T
   IF (T-0.25) 55,57,57
55 T=0.25
57 GT=GT*T
   T1=T1*T
   NN2=0
   DO 58 I=1,N
     A(I)=A(I)-DA(I)
     L(I)=L(I)*T
     DA(I)=DA(I)*T
     A(I)=A(I)+DA(I)
58 CONTINUE
   NN1=NN1+1
   GO TO 52
50 CALL FIX(Z,L,1,N,N9)
   DO 59 I=1,N
59 R(I)=Z(I*(I+1)/2)
   CALL MCONV(Z,N,N9)
   DO 60 I=1,N
60 R(I)=R(I)*Z(I*(I+1)/2)
   CALL FIX(Z,L,0,N,N9)
   IF (EPS) 61,61,62
62 DO 63 I=1,N
63 SIGMA(I)=SQRT(Z(I*(I+1)/2))
61 CALL MVMULT(Z,G,DA,N,N9)
   MAX=1.0
   KAPPA=0
   DO 645 I=1,N
     IF(L(I)) 65,64,65
65 FI=ABS(DA(I)/L(I))
     IF (FI-MAX) 67,67,66
66 MAX=FI
67 FI1=ABS(DA(I)/SIGMA(I))
     IF (FI1-KAPPA) 64,64,68

```



```
68 KAPPA=FI 1
64 CONTINUE
645 CONTINUE
    LAMBDA=1/MAX
    GT=0
    DO 705 I= ,N
        IF(L(I)) 71,70,71
71 IF(NN2-N2) 72,84,84
84 FI=ABS(DA(I)/L(I))
    IF (FI-0.25*MAX) 72,72,73
73 L(I)=L(I)*4.0
72 CONTINUE
    DA(I)=-DA(I)*LAMBDA
    GT=GT+DA(I)*G(I)
70 CONTINUE
705 CONTINUE
    IF (NN3) 74,75,74
74 IF (NN3-N3) 76,75,76
76 IF (KAPPA-0.2) 75,75,77
75 CALL MONITOR(S,N,NN3,A,SIGMA,R,KAPPA,LAMBDA,TETA)
77 IF (KAPPA-ABS(EPS)) 78,78,79
79 IF (NN3-N3) 80,78,78
80 IF (GT) 81,78,78
81 DO 82 I=1,N
82 A(I)=A(I)+DA(I)
    ELDS=S
    NN2=NN2+1
    NN3=NN3+1
    GO TO 51
78 CONTINUE
    RETURN
    END
```


Annexes III.

```

'procedure' Sgz(S,g,z,a,n); 'value' n; 'real' S; 'integer' n;
    'array' g,z,a;
'begin' 'integer' i,t;
    'array' df,ddf[1:n],d[1:128];
    'real' f,e,c,ma;
        S:=0;
        'for' i:=1 'step' 1 'until' n 'do'
            g[i]:=0; t:=n*(n+1)/2;
            'for' i:=1 'step' 1 'until' t 'do'
                z[i]:=0;
        f:=w+1;
        e:=2*w+1;
        'for' t:=6 'step' 1 'until' 123 'do'
'begin' beta[t]:=0;
        ma:=a[n]*x[t]+a[1];
        'for' i:=1 'step' 1 'until' w 'do'
'begin'
    c:=(x[t]-a[f+1])2+a[e+1]2/4;
    beta[t]:=beta[t]+a[1+1]/c;
    df[1+1]:=-ma/c;
    df[f+1]:=-2*ma*a[1+1]*(x[t]-a[f+1])/c2;
    df[e+1]:=-ma*a[1+1]*a[e+1]/(2*c2);
'end';
    df[1]:=1-beta[t];
    df[n]:=x[t]*(1-beta[t]);
        'for' i:=1 'step' 1 'until' n 'do'
            ddf[i]:=df[i];
        'if' eta=7 'then'
'begin' ddf[2*w+2]:=0;
        'for' i:=1 'step' 1 'until' w 'do'
            ddf[2*w+2]:=ddf[2*w+2]+df[2*w+1+1];
        'for' i:=1 'step' 1 'until' w-1 'do'
'begin' ddf[2*w+2+1]:=0;

```



```

1[2*w+2+1]:=0;
a[2*w+2+1]:=a[2*w+2];
'end';
'end';
beta[t]:=0;
  'for' i:=1 'step' 1 'until' w'do'
    beta[t]:=beta[t]+a[i+1]/((x[t]-a[w+1+1])2
      +a[2*w+1+1]2/4);
  beta[t]:=ma*(1-beta[t]);
  'if' y[t]=0 'then' y[t]:=-eta[t];
  d[t]:=-sqrt(y[t]);
form(z,g, d df, beta[t]-y[t],d[t],n);
S:=S+((beta[t]-y[t])/d[t])2
'end'
'end';

```



```

SUBROUTINE SGZ(S,G,Z,A,N,Y,ETA,BETA,B,L,N9)
INTEGER T,W,B,ETA,F,E
REAL MA,L
DIMENSION DF(30),DDF(30),BETA(128),G(N),
CA(N),L(N),Z(N9),Y(128)
S=0
DO 85 I=1,N
85  G(I)=0
    T=N*(N+1)/2
    DO 86 I=1,T
86  Z(I)=0
    W=(N-2)/3
    F=W+1
    E=2*W+1
    DO 87 T=6,123
    BETA(T)=0
    MA=A(N)*T+A(1)
    DO 88 I=1,W
    C=(T-A(F+I))*2+A(E+1)*2/4
    BETA(T)=BETA(T)+A(I+1)/C
    DF(I+1)=-MA/C
    DF(F+I)=-MA*2.0*A(I+1)*(T-A(F+I))/C**2
    DF(E+I)=MA*A(I+1)*A(E+I)/(2*C**2)
88  CONTINUE
    DF(1)=1.0-BETA(T)
    DF(N)=T*(1-BETA(T))
    DO 89 I=1,N
89  DDF(I)=DF(I)
    IF(ETA-7) 855,91,855
91  DDF(2*W+2)=0
    DO 92 I=1,W
92  DDF(2*W+2)=DDF(2*W+2)+DF(2*W+I+1)
    DO 90 I=1,W-1
    DDF(2*W+2+I)=0
    L(2*W+2+I)=0
    A(2*W+2+I)=A(2*W+2)
90  CONTINUE

```



```
855  BETA(T)=0
      DO 93 J=1,W
93    BETA(T)=BETA(T)+A(I+1)/((T-A(F+I))*2+A(E+I)*2/4)
      BETA(T)=MA*(1-BETA(T))
      DT=SQRT(Y(T))
      DTT=BETA(T)-Y(T)
      CALL FORM(Z,G,DDF,DTT,DT,N,N9)
      S=S+(BETA(T)-Y(T))*2/Y(T)
87    CONTINUE

      RETURN
      END
```


Annexes IV.

```

'procedure' Sgz(S,g,z,a,n); 'value' n; 'real' S; 'integer' n;
  'array' g,z,a;
'begin' 'integer' k,nm k,,1,t; .
  'array' ddf,df[1:n];
  'integer' aa,bb,cc;
  'real' kk,tt,mm,yy,xx,zz,ky,ma,k1,t1,m1,y1,x1,z1;
  S:=0; kv:=a[1]2/4;
  'for' i:=1 'step' 1 'until' n 'do'
g[1]:=0;
t:=n*(n+1)/2;
  'for' i:=1 'step' 1 'until' t 'do'
    z[1]:=0;
    'for' t:=6 'step' 1 'until' 123 'do'
'begin' beta[t]:=0;
  ma:=a[2]+a[n]*t;
  df[1]:=0;
  'for' i:=1 'step' 1 'until' w 'do'
'begin' aa:=2+w+1;
  bb:=2+2*w+1;
  cc:=2+3*w+1;
kk:=t+kf1*a[aa]-a[bb]+a[cc];
tt:=t+kfe*a[aa]-a[bb]-a[cc];
mm:=t+kff*a[aa]-a[bb]-a[cc];
yy:=t-kff*a[aa]-a[bb]-a[cc];
xx:=t-kfe*a[aa]-a[bb]-a[cc];
zz:=t-kf1*a[aa]-a[bb]+a[cc];
k1:=sza/(kk2+ky);
t1:=szb/(tt2+ky);
m1:=szc/(mm2+ky);
y1:=szd/(yy2+ky);
x1:=sze/(xx2+ky);
z1:=szf/(zz2+ky);
df[i+2]:=k1+t1+m1+y1+x1+z1;
beta[t]:=beta[t]+a[i+2]*df[i+2];
df[i+2]:=-ma*df[i+2];
k1:=k1/(kk2+ky);
t1:=t1/(tt2+ky);
m1:=m1/(mm2+ky);
y1:=y1/(yy2+ky);
x1:=x1/(xx2+ky);
z1:=z1/(zz2+ky);
  df[1]:=df[1]+a[i+2]*(k1+t1+m1+y1+x1+z1);
kk:=k1*kk;
tt:=t1*tt;
mm:=m1*mm;
yy:=y1*yy;
xx:=x1*xx;
zz:=z1*zz;
k1:=2*ma*a[i+2];
df[bb]:=-k1*(kk+tt+mm+yy+xx+zz);
df[aa]:=-k1*(-kk*kf1-tt*kfe-mm*kff
+yy*kff+xx*kfe+zz*kf1);
df[cc]:=k1*(kk-tt-mm-yy-xx+zz);

```



```

'end';
df[2]:=1-beta[t];
df[n]:=t*df[2];
df[1]:=ma*a[1]/2*df[1];
  'for' i:=1 'step' 1 'until' n 'do'
    ddf[i]:=df[i];
    'if' eta[i]=111
      'then' 'goto' cim;
  'for' k:=1 'step' w 'until' 4*w 'do'
'begin'  'if' eta[k]=5
  'then'
'begin'  ddf[k+2]:=0;
  'for' nn:=0 'step' 1 'until' w-1 'do'
    ddf[k+2]:=ddf[k+2]+df[k+2+nn];
  'for' nn:=1 'step' 1 'until' w-1 'do'
'begin'  ddf[k+2+nn]:=0;
  l[k+2+nn]:=0;
  a[k+2+nn]:=a[k+2];
'end';
  'goto' metka;
'end';
  'if' w=4 'then'
'begin'
  'for' i:=1 'step' 1 'until' 2 'do'
    'for' j:=2 'step' 1 'until' 3 'do'
      'for' nn:=3 'step' 1 'until' 4 'do'
        'for' jk:=4 'step' 1 'until' 5 'do'
'begin'
  'if' (eta[k+1-1]=eta[k+j-1]=eta[k+nn-1]=eta[k+jk-1])
    'and' i<1 'and' j<nn 'and' nn<jk
  'then'
'begin' ddf[k+1+1]:=df[k+1+1]+df[k+1+1]+df[k+1+jk]+df[k+1+nn];
  ddf[k+1+j]:=0;
  ddf[k+1+nn]:=0;
  ddf[k+1+jk]:=0;

  l[k+1+j]:=0;
  l[k+1+nn]:=0;
  l[k+1+jk]:=0;
  a[k+1+j]:=a[k+1+1];
  a[k+1+nn]:=a[k+1+1];
  a[k+1+jk]:=a[k+1+1];
  'goto' metka;
'end';
'end';
'end';
  'if' w=3 'then'
'begin'
  'for' i:=1 'step' 1 'until' 3 'do'
    'for' j:=2 'step' 1 'until' 4 'do'
      'for' nn:=3 'step' 1 'until' 5 'do'
'begin'  'if' (eta[k-1+1]=eta[k-1+j]=eta[k-1+nn])
    'and' i<j 'and' j<nn
    'then'

```



```

'begin'
    ddf[k+1+1]:=df[k+1+j]+df[k+1+1]+df[k+1+nn];
    ddf[k+1+j]:=0;
    ddf[k+1+nn]:=0;
    l[k+1+j]:=0;
    l[k+1+nn]:=0;
    a[k+1+j]:=a[k+1+1];
    a[k+1+nn]:=a[k+1+1];
    'goto' metka;
'end';
'end';
'end';
    'if' w=2 'then'
'begin'
    'for' i:=0 'step' 1 'until' 3 'do'
        'for' j:=2 'step' 1 'until' 5 'do'
'begin'
'if' eta[k+i]=eta[k+j-1]
'and' (k+j-1)>(k+1)
'then'
'begin' ddf[i+k+2]:=df[k+j+1]+df[i+k+2];
        ddf[k+1+j]:=0;
        a[k+1+j]:=a[i+k+2];
        l[k+1+j]:=0;
'end'
'end';
'end';
    metka:'end';
cim: beta[t]:=0;
    'for' i:=1 'step' 1 'until' w 'do'
'begin' aa:=2+w+1;
        bb:=2+2*w+1;
        cc:=2+3*w+1;
        beta[t]:=beta[t]+a[i+2]*(
            sza/((t+kf1*a[aa]-a[bb]+a[cc])12+ky)+
            szb/((t+kfe*a[aa]-a[bb]-a[cc])12+ky)+
            szc/((t+kff*a[aa]-a[bb]-a[cc])12+ky)+
            szd/((t-kff*a[aa]-a[bb]-a[cc])12+ky)+
            sze/((t-kfe*a[aa]-a[bb]-a[cc])12+ky)+
            szf/((t-kf1*a[aa]-a[bb]+a[cc])12+ky));
'end';
        beta[t]:=ma*(1-beta[t]);
        'if' y[t]=0 'then' y[t]:=beta[t];
        ma:=sqrt(y[t]);
        kk:=beta[t]-y[t];
        form(z, g, ddf, kk, ma, n);
        S:=S+(kk/ma)12;
'end'
'end'+

```



```

SUBROUTINE SGZ(S,G,Z,A,N,Y,BETA,B,L,N9,W,SZ,CIS)
INTEGER T,W,B,AA,BB,CC,CIS,Y
REAL S,MA,L,KK,TT,MM,YY,XX,ZZ,KY,KI,TI,MI,YI,XI,ZI
DIMENSION G(N),Z(N9),A(N),Y(CIS),BETA(CIS),L(N),SZ(9),DF(23)
S=0.0
KY=A( )**2/4
DO 854 I=1,N
854 G(I)=0
DO 855 I=1,N9
855 Z(I)=0
II=CIS-5
DO 856 T=6,II
BETA(T)=0
MA=A(2)+A(N)*T
DF( )=0
DO 857 I=1,W
AA=2+W+I
BB=2+2*W+I
CC=2+3*W+I
KK=T+SZ(1)*A(AA)-A(BB)+A(CC)
TT=T+SZ(2)*A(AA)-A(BB)-A(CC)
MM=T+SZ(3)*A(AA)-A(BB)-A(CC)
YY=T-SZ(3)*A(AA)-A(BB)-A(CC)
XX=T-SZ(2)*A(AA)-A(BB)-A(CC)
ZZ=T-SZ(1)*A(AA)-A(BB)+A(CC)
KI=SZ(4)/(KK**2+KY)
TI=SZ(5)/(TT**2+KY)
MI=SZ(6)/(MM**2+KY)
YI=SZ(7)/(YY**2+KY)
XI=SZ(8)/(XX**2+KY)
ZI=SZ(9)/(ZZ**2+KY)

```



```

DF(I+2)=KI+TI+MI+YI+XI+ZI
BETA(T)=BETA(T)+A(I+2)*DF(I+2)
DF(I+2)=-MA*DF(I+2)
KI=KI/(KK**2+KY)
TI=TI/(TT**2+KY)
MI=MI/(MM**2+KY)
YI=YI/(YY**2+KY)
XI=XI/(XX**2+KY)
ZI=ZI/(ZZ**2+KY)
DF(1)=DF(1)+A(I+2)*(KI+TI+MI+YI+XI+ZI)
KK=KI*KK
TT=TI*TT
MM=MI*MM
YY=YI*YY
XX=XI*XX
ZZ=ZI*ZZ
KI=2.0*MA*A(I+2)
11 DF(BB)=-KI*(KK+TT+MM+YY+XX+ZZ)
DF(AA)=-KI*(-KK*SZ(1)-TT*SZ(2)-MM*SZ(3)+YY*SZ(3)+XX*SZ(2)
C+ZZ*SZ(1))
857 DF(CC)=KI*(KK-TT-MM-YY-XX+ZZ)
DF(2)=1-BETA(T)
DF(N)=T*DF(2)
DF( )=MA*A(1)/2*DF( )
BETA(T)=MA*(1-BETA(T))
IF(Y(T)) 861,860,861
860 Y(T)=BETA(T)
861 MA=SQRT(Y(T))
KK=BETA(T)-Y(T)
CALL FORM(Z,G,DF,KK,MA,N,N9)
S=S+(BETA(T)-Y(T))**2/Y(T)
856 CONTINUE
RETURN
END

```


Annexes V.

```

'procedure' EBERLIN (A,S,n,in,nbmax,eps,ef,tausq);
'value' n,in,nbmax,eps,ef;
'array' A,S; 'integer' n,in,nbmax; 'real' eps,ef,tausq;
'begin'
'real' c,d,e,cc,ss,sig,cot,co,s1,h,g,hj,s1,s2,f,ch,
      sh,c1,c2,a',a2;
'integer' i1,nb,dr,di,k,l,i,j; 'for' i:= 1 'step' 1 'until' n 'do'
  'begin' S[i,1]:= 1;
    'for' j:= 1 + 1 'step' 1 'until' n 'do'
      S[i,j]:= S[j,1]:= 0
    'end';
  'for' i1:= 1 'step' 1 'until' in 'do'
    'begin'
eps:= eps/ef;
'for' nb:= 0,nb+1 'while' nb < nbmax 'and' dr + di > 0 'do'
  'begin'
dr:= di:= 0;
'for' i:= 2 'step' 1 'until' n 'do'
'for' j:= 1 'step' 1 'until' i-1 'do'
  'begin' c:= A[i,j] + A[j,i];
    d:= A[i,1] - A[j,j];
    'if' abs(c) < eps 'then'
      'begin' cc:= 1;
        ss:= 0
      'end' 'else'
        'begin' cc:= d/c;
          sig:= 'if' cc = 0 'then' 1 'else' sign(cc);
          cot:= cc + sig * sqrt(1 + cc * cc);
          ss:= sig/sqrt(1 + cot * cot);
          cc:= ss * cot;
          dr:= dr + 1
        'end'
      'end'
    'end'
  'end'
'end'

```



```

'end';
e:= A[1,j] - A[j,1];
ch:= 1; sh:= 0;
'if' abs(e) 'ge' eps 'then'
  'begin' co:= cc * cc - ss * ss;
    si:= 2 * ss * cc;
    h:= g:= hj:= 0;
    'for' k:= 1 'step' 1 'until' n 'do'
      'if' k # 1 'and' k # j 'then'
        'begin' h:= h + A[1,k] * A[j,k] ..
          A[k,1] * A[k,j];
          s1:= A[1,k] ↑ 2 + A[k,j] ↑ 2;
          s2:= A[j,k] ↑ 2 + A[k,1] ↑ 2;
          g:= g + s1 + s2;
          hj:= hj + s1 - s2;
        'end';
        d:= d * co + e * si;
        h:= 2 * h * co - hj * si;
        f:= (2 * e * d - h)/(4 *
          (e * e + d * d) + 2 * g);
      'if' abs(f) 'ge' eps 'then'
        'begin' ch:= 1/sqrt(1 - f * f);
        sh:= f * ch;
        di:= di + 1
        'end'
      'end';
    c1:= ch * cc - sh * ss;
    c2:= ch * cc + sh * ss;
    s1:= ch * ss + sh * cc;
    s2:= sh * cc - ch * ss;
    'if' abs(s1) + abs(s2) # 0 'then'
      'begin' 'for' l:= 1 'step' 1 'until' n 'do'
        'begin' al:= A[1,1];

```



```
a2:= A[1,j];
A[1,1]:= c2 * a1 - s2 * a2;
A[1,j]:= c * a2 - S1 * a1;
a1:= S[1,1];
a2:= S[1,j];
S[1,1]:= c2 * a1 - s2 * a2;
S[1,j]:= c * a2 - S1 * a1;
'end';
'for' L:= 1 'step' 1 'until' n 'do'
'begin' a1:= A[1,1];
a2:= A[j,1];
A[1,1]:= c1 * a1 + s1 * a2;
A[j,1]:= c2 * a2 + s2 * a1;
'end';
'end';
'end';
'end';
'end';
tausq:= 0;

'for' i:= 1 'step' 1 'until' n 'do'
'for' j:= i + 1 'step' 1 'until' n 'do'
tausq:= tausq + A[1,j] ↑ 2 + A[j,1] ↑ 2;
'end';
```



```

'procedure' sgz(S,g,z,a,n); 'value' n; 'real' S; 'integer' n;
    'array' g,z,a;
'begin' 'integer' i,j,t,nn,k,w5,w6,w7,w8,w9,w10,w11,w12;
'integer' w2,w3,w4,w5,w6,w7,w8,w9,w10,w11,w12;
    'array' df,ddf[1:n],
        t1,t2,t3,t4,t5,t6,t7,t8,t9,t10,t11,t12,th,
        te,tte,tf1,tet[1:12],b3,b4[1:4],
        ta,tb[1:8,1:8],r[1:12],p1,p2,p3,p4,p5,p6,p7,p8,p9,p10,p11,p12,pk[1:4],pv[1:
8,1:4],thh[1:12];
'real' mutte,mutf1,dt,dtm;
    'real' kyy,ky,t1,ki,m1,y1,x1,z1,b1,a1,kk,tt,mm,yy,zz,xx,ma;
S:=0;
    'for' i:=1 'step' 1 'until' n 'do'
        g[i]:=0;
        t:=n*(n+1)/2;
    'for' i:=1 'step' 1 'until' t 'do'
        z[i]:=0;
    'for' i:=1 'step' 1 'until' w 'do'
'begin'    w4:=i+1+w*4;
        w8:=i+1+w*8;
        w10:=i+1+w*10;
        w11:=i+1+w*11;
        w12:=i+1+w*12;
th[1]:=th[1+4]:=th[1+6]:=th[1+8]:=th[1+10]:=koef1*a[w4];
th[1+2]:=koef1*((1+koef4)*a[w4]);
thh[1]:=thh[1+4]:=thh[1+6]:=thh[1+8]:=thh[1+10]:=a[w4];
thh[1+2]:=a[w4]*(1+koef4);
te[1]:=te[1+2]:=te[1+6]:=te[1+8]:=te[1+10]:=a[w8];
te[1+4]:=a[w8]*(1+koef5);
tte[1]:=tte[1+2]:=tte[1+8]:=tte[1+10]:=tte[1+4]:=a[w10];
tte[1+6]:=a[w10]*(1+koef6);
tf1[1]:=tf1[1+2]:=tf1[1+4]:=tf1[1+6]:=tf1[1+10]:=a[w11];
tf1[1+8]:=a[w11]*(1+koef7);
tet[1]:=tet[1+2]:=tet[1+4]:=tet[1+6]:=tet[1+8]:=a[w12];
tet[1+10]:=a[w12]*(1+koef8);
'end';
    'for' i:=1 'step' 4 'until' 12 'do'
'begin'    kk:=sin(tte[i]);
        tt:=sin(tf1[i]);
        mm:=cos(tf1[i]);

```



```

yy:=cos(tte[1]);
xx:=3*te[1];
zz:=th[1]*yy;
ta[1,1]:=ta[5,5]:=xx-1.5*zz;
ta[1,3]:=ta[5,7]:=ta[2,4]:=ta[6,8]:=ta[3,1]:=ta[7,5]:=ta[4,2]:=ta[8,6]:=
1.732*tet[1]*te[1];
ta[2,2]:=ta[6,6]:=-xx-0.5*zz;
ta[2,3]:=ta[6,7]:=ta[3,2]:=ta[7,6]:=-th[1]*kk*mm;
ta[ ,2]:=ta[5,6]:=ta[3,4]:=ta[7,8]:=ta[2,1]:=ta[6,5]:=ta[4,3]:=ta[8,7]:=
ta[2,3]*0.866;
ta[3,3]:=ta[7,7]:=-xx+0.5*zz;
ta[4,4]:=ta[8,8]:=xx+4.5*zz;
ta[6,3]:=ta[3,6]:=th[1]*kk*tt;
ta[2,7]:=ta[7,2]:=-ta[6,3];
ta[5,2]:=ta[2,5]:=ta[7,4]:=ta[4,7]:=ta[6,3]*0.866;
ta[1,6]:=ta[6,1]:=ta[3,8]:=ta[8,3]:=-ta[5,2];
ta[1,4]:=ta[5,8]:=ta[4,1]:=ta[8,5]:=ta[5,1]:=ta[5,3]:=
ta[5,4]:=ta[6,2]:=ta[6,4]:=ta[7,1]:=ta[7,3]:=ta[8,1]:=
ta[8,2]:=ta[8,4]:=ta[4,5]:=ta[4,7]:=ta[4,8]:=ta[2,6]:=
ta[2,8]:=ta[3,5]:=-ta[3,7];
ta[4,5]:=ta[4,6]:=ta[4,8]:=0;
EBERLIN(ta,tb,8,3,25,1&-5,10,dk);
k:=1;
'for' i:=4 'step' 1 'untill' 7 'do'
  'for' j:=2 'step' 1 'untill' 8 'do'
    'begin' 'if' abs(ta[i,i]-ta[j,j])<koef3
      'and' j>i 'then'
        'begin' pk[k]:=ta[i,i];
          'for' nn:=4 'step' 1 'untill' 8 'do'
            pv[nn,k]:=tb[nn,i];
          k:=k+1;
        'end';
      'end';
    kk:=koef2*0.5*th[1];
    t11[1]:=pk[1]+kk;
    t12[1]:=pk[1]-kk;
    t13[1]:=pk[2]+kk;
    t14[1]:=pk[2]-kk;
    t21[1]:=pk[3]+kk;
    t22[1]:=pk[3]-kk;
    t23[1]:=pk[4]+kk;
    t24[1]:=pk[4]-kk;

```



```

mutte:=tte[1];
mutf1:=tf1[1];
mla1: vektor(pv, mutte, mutf1, b4, b3);
p11[1]:=b3[1]*kff;
p12[1]:=b4[1]*kff2;
p13[1]:=b3[2]*kff3;
p14[1]:=b4[2]*kff4;
p21[1]:=b3[3]*kff5;
p22[1]:=b4[3]*kff6;
p23[1]:=b3[4]*kff7;
p24[1]:=b4[4]*kff8;
'end';
'for' t:=6 'step' 1 'until' cis-5 'do'
'begin'
beta[t]:=0;
gamma[t]:=0;
ma:=a[1]+a[n]*x[t];
'for' i:=1 'step' 1 'until' w 'do'
'begin' w5:=1+i+5*w;
w7:=1+i+7*w;
w9:=1+i+9*w;
w3:=1+i+w*3;
ky:=a[1+w+1]^2/4;
kk:=x[t]+kff1*a[w5]-a[w7]+a[w9];
tt:=x[t]+kff2*a[w5]-a[w7]-a[w9];
mm:=x[t]+kff3*a[w5]-a[w7]-a[w9];
yy:=x[t]-kff4*a[w5]-a[w7]-a[w9];
xx:=x[t]-kff5*a[w5]-a[w7]-a[w9];
zz:=x[t]-kff6*a[w5]-a[w7]+a[w9];
ki:=kk^2+ky;
ti:=tt^2+ky;
mi:=mm^2+ky;
yi:=yy^2+ky;
xi:=xx^2+ky;
zi:=zz^2+ky;
bi:=ma*a[w3];
df[w3]:=sza/ki+szb/ti+szc/mi+szd/yi+sze/xi+szf/zi;
df[1+w+1]:=bi*a[1+w+1]/2*(sza/ki^2+szb/ti^2+szc/mi^2+
szd/yi^2+sze/xi^2+szf/zi^2);

```



```

beta[t]:=beta[t]+a[w3]*df[w3];
kmk[t,1]:=beta[t];
df[w3]:=-ma*df[w3];
kk:=kk/k1↑2*sza;
tt:=tt/t1↑2*szb;
mm:=mm/m1↑2*sze;
yy:=yy/y1↑2*szd;
xx:=xx/x1↑2*sze;
zz:=zz/z1↑2*szf;
df[w5]:=-2*b1*(-kfl*kk-kfe*tt-kff*mm
+kff*yy+kfe*xx+kfl*zz);
df[w7]:=-2*b1*(kk+tt+mm+yy+xx+zz);
df[w9]:=2*b1*(kk-tt-mm-yy-xx+zz);
w2:=4+1+w*2;
w6:=4+1+w*6;
ky:=a[1+1]↑2/4;
t1:=x[t]-a[w6]-t11[1];
k1:=x[t]-a[w6]-t12[1];
m1:=x[t]-a[w6]-t13[1];
y1:=x[t]-a[w6]-t14[1];
x1:=x[t]-a[w6]-t21[1];
z1:=x[t]-a[w6]-t22[1];
b1:=x[t]-a[w6]-t23[1];
a1:=x[t]-a[w6]-t24[1];
tt:=t1↑2+ky;
kk:=k1↑2+ky;
mm:=m1↑2+ky;
yy:=y1↑2+ky;
xx:=x1↑2+ky;
zz:=z1↑2+ky;
mutte:=b1↑2+ky;
mutfi:=a1↑2+ky;
df[w2]:=-ma*(p11[1]/tt+p12[1]/kk+p13[1]/mm+p14[1]/yy+
p21[1]/xx+p22[1]/zz+p23[1]/mutte+p24[1]/mutfi);
df[w6]:=-2*ma*a[w2]*(p11[1]*t1/tt↑2+p12[1]*k1/kk↑2+
p13[1]*m1/mm↑2+p14[1]*y1/yy↑2+
p21[1]*x1/xx↑2+p22[1]*z1/zz↑2+
p23[1]*b1/mutte↑2+p24[1]*a1/mutfi↑2);

```



```

    df[i+1]:=a[i+1]/2*ma*a[w2]*(
p11[i]/tt[i2+p12[i]/kk[i2+p13[i]/mm[i2+p14[i]/yy[i2+
p21[i]/xx[i2+p22[i]/zz[i2+p23[i]/mutte[i2+p24[i]/mutr[i2);
    gamma[t]:=gamma[t]+a[w2]*(-df[w2])/ma;
'end';
beta[t]:=beta[t]+gamma[t];
    df[1]:=1-beta[t];
    df[n]:=x[t]*df[1];
    beta[t]:=ma*df[1];
    'for'j:=0'step'2'unt11'10'do'
        'for'i:=1'step'1'unt11'w'do'
'begin'    ky:=a[i+1]i2/4;
            w6:=1+i+w*6;
            r[1+j]:=a[1+i+w*2]*((p11[1+j]/((x[t]-a[w6]-t11[1+j])i2+ky)+
                p12[1+j]/((x[t]-a[w6]-t12[1+j])i2+ky)+
                p13[1+j]/((x[t]-a[w6]-t13[1+j])i2+ky)+
                p14[1+j]/((x[t]-a[w6]-t14[1+j])i2+ky)+
                p21[1+j]/((x[t]-a[w6]-t21[1+j])i2+ky)+
                p22[1+j]/((x[t]-a[w6]-t22[1+j])i2+ky)+
                p23[1+j]/((x[t]-a[w6]-t23[1+j])i2+ky)+
                p24[1+j]/((x[t]-a[w6]-t24[1+j])i2+ky));
'end';

```



```

'for' i:=1'step'1'until'w'do'
'begin' df[i+1+w*4]:=ma*(f[i]-f[i+2])/(a[i+1+w*4]*koef4);
      df[i+1+w*8]:=ma*(f[i]-f[i+4])/(a[i+1+w*8]*koef5);
      df[i+1+w*10]:=ma*(f[i]-f[i+6])/(a[i+1+w*10]*koef6);
      df[i+1+w*11]:=ma*(f[i]-f[i+8])/(a[i+1+w*11]*koef7);
      df[i+1+w*12]:=ma*(f[i]-f[i+10])/(a[i+1+w*12]*koef8);
'end';

'for' i:=1'step'1'until'n'do'
  ddf[i]:=df[i];
  'if' eta[i]=111'then' 'goto' c1m;
  'if' eta[i]=222'then'
'begin' ddf[2]:=df[2]+df[4]+df[5];
      'for' nn:=2'step'1'until'3'do'
'begin' ddf[nn+2]:=0;
      a[nn+2]:=a[2];
      l[nn+2]:=0;
'end';
'end';

'if' eta[5]=333'then'
'begin' ddf[6]:=df[6]+df[8]+df[9];
      'for' nn:=2'step'1'until'3'do'
'begin' ddf[nn+6]:=0;
      a[nn+6]:=a[6];
      l[nn+6]:=0;
'end';
'end';

beta[t]:=gamma[t]:=0;
'for' i:=1'step'1'until'w'do'
'begin' w5:=1+i+w*5;
      w3:=1+i+3*w;
      w7:=1+i+7*w;
      w9:=1+i+9*w;
      w6:=1+i+w*6;
      ky:=a[i+w+1]*t2/4;
beta[t]:=beta[t]+(a[w3]*(sza/((x[t]+kfi*a[w5]-a[w7]+a[w9])2+ky)+
      szb/((x[t]+kfe*a[w5]-a[w7]-a[w9])2+ky)+

```



```

szc/((x[t]+kff*a[w5]-a[w7]-a[w9])^2+ky)+
szd/((x[t]-kff*a[w5]-a[w7]-a[w9])^2+ky)+
sze/((x[t]-kfe*a[w5]-a[w7]-a[w9])^2+ky)+
szf/((x[t]-kfi*a[w5]-a[w7]+a[w9])^2+ky));

kyy:=a[i+1]^2/4;
gamma[t]:=gamma[t]+(a[i+1+w*2]*
((p1[1]/((x[t]-a[w6]-t1[1])^2+kyy))+
(p2[1]/((x[t]-a[w6]-t2[1])^2+kyy))+
(p3[1]/((x[t]-a[w6]-t3[1])^2+kyy))+
(p4[1]/((x[t]-a[w6]-t4[1])^2+kyy))+
(p21[1]/((x[t]-a[w6]-t21[1])^2+kyy))+
(p22[1]/((x[t]-a[w6]-t22[1])^2+kyy))+
(p23[1]/((x[t]-a[w6]-t23[1])^2+kyy))+
(p24[1]/((x[t]-a[w6]-t24[1])^2+kyy))));

'end';
beta[t]:=ma*(1-beta[t]-gamma[t]);
cim: 'if' y[t]=b*65535 'or' al[t]=1
'then'
'begin' y[t]:=beta[t];
al[t]:=1;
'end';
dtt:=sqrt(y[t]);
dmt:=beta[t]-y[t];
form(z,g,ddf,dmt,dtt,n):
S:=S+(beta[t]-y[t])^2/y[t];
'end';
'end';

```



```

SUBROUTINE VEKTOR (VK,RTE,RFI,B3,B4)
COMPLEX V,CA21,CA22,CEXPFI
DIMENSION V(4,4),VK(8,4),B3(4),B4(4)
Q=0.57735026919
CEXPFI=CMPLX(COS(RFI),-SIN(RFI))
F=0.5*RTE
CA11=SIN(F)
CA12=COS(F)
DO 15 I=1,4
DO 15 J=1,4
15 V(I,J)=CMPLX(VK(I,J),VK(I+4,J))
CA21=-CA12*CEXPFI
CA22=+CA11*CEXPFI
DO 17 J=1,4
OB3(J)=((CABS(CA11*V(1,J)+Q*CA11*V(3,J)
1+CA21*V(4,J)+Q*CA21*V(2,J)))**2
2+(CABS(CA11*V(1,J)-Q*CA11*V(3,J)
3-CA21*V(4,J)+Q*CA21*V(2,J)))**2
4+(CABS(CA11*V(2,J)+CA21*V(3,J)))**2*1.3333333333)*4.1887902048
OB4(J)=((CABS(CA12*V(1,J)+Q*CA12*V(3,J)
1+CA22*V(4,J)+Q*CA22*V(2,J)))**2
2+(CABS(CA12*V(1,J)-Q*CA12*V(3,J)
3-CA22*V(4,J)+Q*CA22*V(2,J)))**2
4+(CABS(CA12*V(2,J)+CA22*V(3,J)))**2*1.3333333333)*4.1887902048
17 CONTINUE
RETURN
END

```


Annexes VI.

```

'begin' 'integer' n, nn;
      nn:=read;
      n:=read;
      newline(3); space(50);
      writetext(('program%Jgja')); newline(3);
'begin' 'array' s, x, y, z, x1, y1, z1[1:n], f[1:9], u[1:3],
      ta, tb[1:3, 1:3], x2, y2, z2, s2[1:n, 1:nn], mm[1:11, 1:nn];
      'integer' i, d, w, k, t, j, m, xa, xb, jj;
'real' aa, ba, ca, da, a, b, c, r, r2, r3, r5, q, p,
      u1, v, l1, l2, l3, ka, kb, kc, a1, b1, c1;
'procedure' jakobi(n, rho, a, s);
      'value' n, rho;
'integer' n;
'real' rho;
'array' a, s;
'begin' 'real' norm1, norm2, thr, mu, omega, sint, cost, int1, v1, v2, v3;
      'integer' i, j, p, q, ind;
      'for' i:=1 'step' 1 'until' n 'do'
        'for' j:=1 'step' 1 'until' i 'do'
          'if' i=j 'then' s[i, j]:=1 'else' s[i, j]:=a[j, i]:=0;
      int1:=0;
      'for' i:=2 'step' 1 'until' n 'do'
        'for' j:=1 'step' 1 'until' i-1 'do'
          int1:=int1+2*a[i, j]2;
      norm1:=thr:=sqrt(int1);
      norm2:=(rho/n)*norm1;
      ind:=0;
      main: thr:=thr/n;
      main1: 'for' q:=2 'step' 1 'until' n 'do'
        'for' p:=1 'step' 1 'until' q-1 'do'
          'if' abs(a[p, q])>thr 'then'
'begin' ind:=1;
      v1:=a[p, p];
      v2:=a[p, q];
      v3:=a[q, q];

```



```

mu:=0.5*(v1-v3);
omega:='if' mu=0'then'-1'else'-sign(mu)*v2/sqrt(v2↑2+mu↑2);
sint:=omega/sqrt(2*(1+sqrt(1-omega↑2)));
cost:=sqrt(1-sint↑2);
  'for' i:=1'step'1'until'1'n'do'
'begin'  int1:=a[1,p]*cost-a[1,q]*sint;
        a[1,q]:=a[1,p]*sint+a[1,q]*cost;
        a[1,p]:=int1;
        int1:=s[1,p]*cost-s[1,q]*sint;
        s[1,q]:=s[1,p]*sint+s[1,q]*cost;
        s[1,p]:=int1;
'end';
  'for' i:=1'step'1'until'1'n'do'
'begin'  a[p,1]:=a[1,p];
        a[q,1]:=a[1,q];
'end';
  a[p,p]:=v1*cost↑2+v3*sint↑2-2*v2*sint*cost;
  a[q,q]:=v1*sint↑2+v3*cost↑2+2*v2*sint*cost;
  a[p,q]:=a[q,p]:=(v1-v3)*sint*cost+v2*(cost↑2-sint↑2);
'end';
  'if' ind=1'then'
'begin'  ind:=0;
        'go to' main1
'end';
'if' thr>norm2'then' 'go to' main;
'end';
  'for' j:=1'step'1'until'1'n'do'
'begin'  'for' i:=1'step'1'until'1'1'do'
        mm[1,j]:=read;
        'for' i:=1'step'1'until'1'n'do'
'begin'  x2[1,j]:=read;
        y2[1,j]:=read;
        z2[1,j]:=read;
        s2[1,j]:=read;
'end';
'end';

```



```

'end';
'for' jj:=1 'step' 1 'until' nn 'do'
'begin'  xa:=mm[1,jj];
        xb:=mm[2,jj];
        w:=mm[3,jj];
        a:=mm[4,jj];
        b:=mm[5,jj];
        c:=mm[6,jj];
        v:=mm[7,jj];
        l1:=mm[8,jj];
        l2:=mm[9,jj];
        l3:=mm[10,jj];
        m:=mm[11,jj];
        'for' i:=1 'step' 1 'until' n 'do'
'begin'  x1[1]:=x2[1,jj];
        y1[1]:=y2[1,jj];
        z1[1]:=z2[1,jj];
        s[1]:=s2[1,jj];
'end';
newline(3);
space(30); writetext(('nomer%ser11'));
space(3); print(xb,4,0); newline(2);
space(30); writetext(('nuleva ja%toeska'));
space(3); print(w,3,0);
newline(2);
ka:=0;
kb:=0;
kc:=0;
space(20); writetext(('x'));
space(20); writetext(('y'));
space(20); writetext(('z'));
space(20); writetext(('s'));
newline(2);
'for' i:=1 'step' 1 'until' n 'do'
'begin'  space(15); print(x1[1],2,5);
        space(12); print(y1[1],2,5);

```



```
space(12); print(z1[1],2,5);
space(12); print(s[1],2,5);
newline(1);
'end';
  'for'd:=1'step'1'until'xa'do'
'begin' newline(2);
  space(10); writetext('('sag')');
  space(3); print(xa,2,0);
  space(3); writetext('('ka=')');
  print(ka,2,6); space(3); writetext('('kb=')');
  print(kb,2,6); space(3); writetext('('kc=')');
  print(kc,2,6); newline(1);
    a:=a+ka;
    b:=b+kb;
    c:=c+kc;
  'for'i:=1'step'1'until'n'do'
'begin'  x[1]:=x1[1];
        y[1]:=y1[1];
        z[1]:=z1[1];
end';
  a1:=x[w];
  b1:=y[w];
  c1:=z[w];
'for'i:=1'step'1'until'n'do'
'begin' x[1]:=(x[1]-a1)*a;
        y[1]:=(y[1]-b1)*b;
        z[1]:=(z[1]-c1)*c;
end';
  'for'i:=1'step'1'until'9'do'
    f[1]:=0;
    'for'k:=-m'step'1'until'm'do'
      'for't:=-m'step'1'until'm'do'
        'for'i:=-m'step'1'until'm'do'
          'for'j:=1'step'1'until'n'do'
'begin' 'if'k=0'and't=0'and'i=0'and'j=w 'then'
        'go to' mk;
```



```
r2:=(x[j]+a*1)2+(y[j]+b*t)2+(z[j]+c*k)2;
r3:=r2*sqrt(r2);
r5:=r3*r2;
f[1]:=f[1]+((3*(x[j]+a*1)2/r2-1)*s[j]/r3);
f[2]:=f[2]+(3*s[j]*(x[j]+a*1)*(y[j]+b*t)/r5);
f[3]:=f[3]+(3*s[j]*(x[j]+a*1)*(z[j]+c*k)/r5);
f[4]:=f[2];
f[5]:=f[5]+((3*(y[j]+b*t)2/r2-1)*s[j]/r3);
f[6]:=f[6]+(3*s[j]*(y[j]+b*t)*(z[j]+c*k)/r5);
f[7]:=f[3];
f[8]:=f[6];
f[9]:=f[9]+((3*(z[j]+c*k)2/r2-1)*s[j]/r3);
mk: 'end';
  newline(4);
    'for' i:=1 'step' 1 'until' 9 'do'
'begin' print(f[i],0,8); newline(1);
'end';      k:=0;
    'for' i:=1 'step' 1 'until' 3 'do'
'begin'   'for' j:=1 'step' 1 'until' 3 'do'
          ta[1,j]:=f[j+k];
          k:=k+3;
'end';

      jakobi(3,1&-8,ta,tb);
      u[1]:=ta[1,1];
      u[2]:=ta[2,2];
      u[3]:=ta[3,3];
      newline(1);
      writetext(('vektor')); newline(1);
      'for' i:=1 'step' 1 'until' 3 'do'
        'for' j:=1 'step' 1 'until' 3 'do'
'begin' space(3);
        print(tb[j,1],8,8);
        newline(1);
'end';
      space(2); writetext(('korn1'));
      newline(2);
      'for' i:=1 'step' 1 'until' 3 'do'
```



```
'begin'  print(u[1],0,8);
        newline(1);
'end';
        'for' i:=1 'step' 1 'until' 2 'do'
'begin'  u1:=u[i];
        t:=1;
        'for' j:=i+1 'step' 1 'until' 3 'do'
'if' abs(u[j])>abs(u1) 'then'
'begin'  u1:=u[j];
        t:=j;
'end';
        'if' t#1 'then'
'begin'  u[t]:=u[1];
        u[1]:=u1;
'end';
'end';
        aa:=(u[3]-u[2])/u[1];
        ba:=u[1];
        ca:=v*ba*(1+aa2/3)10.5;
        newline(1);
        space(10);
        writetext(('kvadrupolnoe%raszseplenie'));
        space(10);
        writetext(('gradient'));
        space(10);
        writetext(('parametr%aszsimetrii'));
        space(10);
        writetext(('parametr%resetki'));
        newline(1);
        space(20); print(ca,1,3);
        space(10); print(ba,3,5);
        space(8);  print(aa,3,5);
        space(10); print(a,2,5);
        space(3); print(b,2,5);
        space(3); print(c,2,5);
```



```
ka:=11;
kb:=12;
kc:=13;
newline(2);
'end';
'end';
  writetext('('konec')');
'end';
'end';
```


Annexes VII.

```

MASTER JGGR
INTEGER D,K,T
REAL L1,L2,L3
DIMENSION S(100),X(100),Y(100),Z(100),X1(100),Y1(100),Z1(100),
CF(9),U(3),TA(3,3),TB(3,3)
5 READ (11,5)N,NA,NW,A,B,C,V,L1,L2,L3,M
6 FORMAT(10,I0,I0,I0,FO.0,FO.0,FO.0,FO.0,FO.0,FO.0,FO.0,I0,)
7 READ (11,6)(X1(I),Y1(I),Z1(I),S(I),I=1,N)
8 FORMAT(FO.0,FO.0,FO.0,FO.0,)
9 WRITE(10,7)
10 FORMAT(1H0,)
KA=0
KB=0
KC=0
DO 10 D=1,NA,1
A=A+KA
B=B+KB
C=C+KC
DO 11 I=1,N,1
11 X(I)=X1(I)
Y(I)=Y1(I)
Z(I)=Z1(I)
A1=X(NW)
B1=Y(NW)
C1=Z(NW)
DO 12 I=1,N,1
12 X(I)=(X(I)-A1)*A
Y(I)=(Y(I)-B1)*B
Z(I)=(Z(I)-C1)*C
DO 13 I=1,9,1
13 F(I)=0
L=2*M+1
DO 14 K=1,L
DO 14 T=1,L
DO 14 I=1,L
DO 14 J=1,N
IF(K-M-1) 18,15,18
15 IF(T-M-1) 18,16,18
16 IF(I-M-1) 18,17,18
17 IF(J-NW) 18,100,18
18 R2=(X(J)+A*(I-M-1))**2+(Y(J)+B*(T-M-1))**2+(Z(J)+C*(K-M-1))**2
R3=R2*SQRT(R2)
R5=R2*R3
F(1)=F(1)+((3*(X(J)+A*(I-M-1))**2/R2-1)*S(J)/R3)
F(2)=F(2)+{3*S(J)*(X(J)+A*(I-M-1))*(Y(J)+B*(T-M-1))/R5}
F(3)=F(3)+{3*S(J)*(X(J)+A*(I-M-1))*(Z(J)+C*(K-M-1))/R5}
F(4)=F(2)
F(5)=F(5)+((3*(Y(J)+B*(T-M-1))**2/R2-1)*S(J)/R3)
F(6)=F(6)+{3*S(J)*(Y(J)+B*(T-M-1))*(Z(J)+C*(K-M-1))/R5}
F(7)=F(3)
F(8)=F(6)
F(9)=F(9)+((3*(Z(J)+C*(K-M-1))**2/R2-1)*S(J)/R3)
100 MLL= 0

```



```

14  CONTINUE
    WRITE(10,50)NW
50  FORMAT(//,30X,12HPROGRAM JGGR,/,15X,15HNULEVAJA TOCSKA,2X,3HNW=,
    CI2,///,)
    WRITE(10,51)(F(I),I= ,9)
51  FORMAT(4X,E15.8)
    K=0
    DO 49 I=1,3,1
    DO 20 J=1,3,1
20  TA(I,J)=F(J+K)
    K=K+3
19  CONTINUE
    CALL JAKOBG(3,0.00000001,TA,TB)
    U( )=TA(1,1)
    U(2)=TA(2,2)
    U(3)=TA(3,3)
    WRITE(10,70)
70  FORMAT(/,3X,6HVEKTOR,/,)
    DO 71 J=1,3
    WRITE(10,72)(TB(I,J),I=1,3)
72  FORMAT(/,3X,F15.8,)
71  CONTINUE
    WRITE(10,73)
73  FORMAT(/,3X,5HKORNI,/,)
    WRITE(10,53)(U(I),I= ,3)
53  FORMAT(/,3X,F15.8,)
    DO 25 I=1,2,1
    U1=U(I)
    T=I
    DO 27 J=I+1,3,1
    IF (ABS(U(J)-ABS(U1))) 27,27,28
28  U1=U(J)
    T=J
27  CONTINUE
    IF(T-I)29,120,29
29  U(T)=U(I)
    U(I)=U1
20  CONTINUE
25  CONTINUE
    AA=(U(3)-U(2))/U(1)
    BA=U(1)
    CA=V*BA*(1+AA**2/3)**0.5
    WRITE(10,55) CA,BA,AA,A,B,C
55  FORMAT(/,10X,25HKVADRUPOLOE RASZSEPLENIE,5X,8HGRADIENT,10X,
    C20HPARAMETER ASZIMETRII,10X,17HPARAMETER RESETKI,/,20X,F8.5,10X,
    CF8.5,8X,F8.5,10X,F7.5,3X,F7.5,3X,F7.5,/,)
    KA=L1
    KB=L2
    KC=L3
10  CONTINUE
    WRITE(10,56)
56  FORMAT(//,10X,5HKONEC,/,)
    STOP
    END

```



```

SUBROUTINE JAKOBG (N,RHO,A,S)
REAL MU
DIMENSION S(N,N),A(N,N)
DO 10 I=1,N
DO 10 J=1,I
IF (I-J) 2,14,12
14 S(I,J)=
GO TO 11
12 S(I,J)=0
S(J,I)=0
11 CONTINUE
10 CONTINUE
XINT1=0
DO 15 I=2,N
II=I-1
DO 15 J=1,II
XINT1=XINT1+2*A(I,J)**2
15 CONTINUE
XNORM1=SQRT(XINT1)
THR=SQRT(XINT1)
XNORM2=(RHO/N)*XNORM1
IND=0
16 THR=THR/N
17 DO 8 IQ=2,N
IIP=IQ-1
DO 18 IP=1,IIP
IF (ABS(A(IP,IQ))-THR) 19,19,20
20 IND=1
V1=A(IP,IP)
V2=A(IP,IQ)
V3=A(IQ,IQ)
MU=0.5*(V1-V3)
IF (MU=0) 22,21,22
21 OMEGA=-1
GO TO 23
22 OMEGA=-SIGN(MU)*V2/SQRT(V2**2+MU**2)
23 SINT=OMEGA/SQRT(2*(+SQRT(-OMEGA**2)))
COST=SQRT(1-SINT**2)
DO 24 I=1,N
XINT1=A(I,IP)*COST-A(I,IQ)*SINT
A(I,IQ)=A(I,IP)*SINT+A(I,IQ)*COST
A(I,IP)=XINT1
XINT1=S(I,IP)*COST-S(I,IQ)*SINT
S(I,IQ)=S(I,IP)*SINT+S(I,IQ)*COST
S(I,IP)=XINT1
24 CONTINUE
DO 25 I=1,N
A(IP,I)=A(I,IP)
A(IQ,I)=A(I,IQ)
25 CONTINUE
A(IP,IP)=V1*COST**2+V3*SINT**2-2*V2*SINT*COST
A(IQ,IQ)=V1*SINT**2+V3*COST**2+2*V2*SINT*COST
A(IP,IQ)=(V1-V3)*SINT*COST+V2*(COST**2-SINT**2)
A(IQ,IP)=A(IP,IQ)
19 CONTINUE
18 CONTINUE
IF (IND=1) 27,26,27
26 IND=0
GO TO 7
27 IF (THR-XNORM2) 29,29,28
28 GO TO 16
29 KKK=0
RETURN
END

```


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